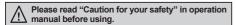
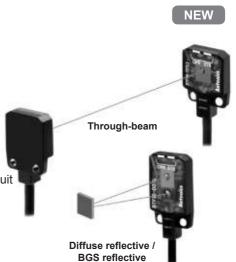
Ultra-slim and amplifier built-in type

Features

- Realization of ultra-slim size by adopting one-chip photo IC
- Size: Through-beam(W13×H19×L3.7mm),
 Diffuse reflective, BGS reflective(W13×H24×L3.7mm)
- Adopts BGS method superior than convergent reflective to minimize error by background color, or material of sensing object for stable sensing
- Visible light source to check the position of sensing spot and superior to small sensing target with narrow sensing width
- Built-in reverse polarity, output short, overcurrent protection circuit
- Protection structure IP67(IEC standard)







Specifications

N G	PN open collector output	BTF1M-TDTL	BTF1M-TDTD	BTF30-DDTL	BTF30-DDTD	BTF15-BDTL	BTF15-BDTD	
Model N	NP open collector output	BTF1M-TDTL-P	BTF1M-TDTD-P	BTF30-DDTL-P	BTF30-DDTD-P	BTF15-BDTL-P	BTF15-BDTD-P	
Sensing type		Through-beam		Diffuse reflective		BGS reflective		
Sensing distance		1m		5 to 30mm (Non-glossy white paper 50×50mm)		1 to 15mm (Non-glossy white paper 50×50mm)		
Sensing target		Opaque materials of max. ø2mm		Opaque materials, Translucent materials				
Min.sensing target		Opaque materials of ø2mm		ø0.2mm (Sensing distance 10mm)		ø0.2mm non-illuminated objects (Sensing distance 10mm)		
Hysteresis		_		Max. 20% at rated sensing distance		Max. 5% at rated sensing distance		
Reflectivity characteristics (black/white error)		_		_		Max. 15% of maximum sensing distance		
Response time		Max. 1ms						
Power supply		12-24VDC ±10%(Ripple P-P: Max. 10%)						
Current consumption		Max. 20mA(This is for each emitter and receiver of through-beam type)						
Light source		Red LED(650nm)						
Operation mode		Light ON	Dark ON	Light ON	Dark ON	Light ON	Dark ON	
Control output		NPN or PNP open collector output •Load voltage: Max. 26.4VDC •Load current: Max. 50mA •Residual voltage - NPN:Max. 1V, PNP:Max. 2V						
Protection circuit		Reverse polarity protection, output short-circuit protection						
Indicator		Operation indicator: Red, Stability indicator: Green						
Insulation resistance		Min. 20MΩ(at 500VDC megger)						
Noise resistance		±240V the square wave noise(pulse width:1μs) by the noise simulator						
Dielectric strength		1,000VAC 50/60Hz for 1 minute						
Vibration		1.5mm amplitude or 300m/s² at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours						
Shock		500m/s²(approx. 50G) in each of X, Y, Z directions for 3 times						
Enviror	Ambient illumination	Sunlight: Max. 10,0001x Incandescent lamp: Max. 3,0001x (Receiver illumination)						
	Ambient temperature	-25 to 55°C, storage: -40 to 70°C						
	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH						
Protection		IP67(IEC standards)						
Material		Case: PBT, Sensing part : PMMA						
Cable		ø2.5, 3-wire, Length: 2m (Emitter of through-beam type: ø2.5, 2-wire, Length: 2m) (AWG28, Core diameter: 0.08mm, Number of cores: 19, Insulator out diameter: ø0.9)						
Accessory		Fixing bracket(SUS304), Bolt(SWCH10A)						
Approval		CE						
Unit v	veight	Approx. 40g		Approx. 25g				

**The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

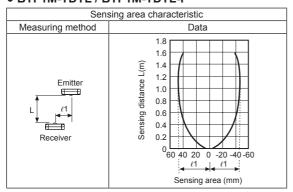
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Ultra-Slim and Amplifier Built-in type

■ Feature data

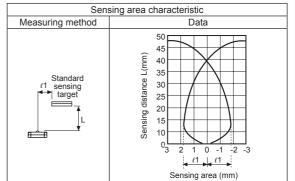
Through-beam

BTF1M-TDTL / BTF1M-TDTL-P



O Diffuse reflective

BTF30-DDTL / BTF30-DDTL-P



(B) Fiber optic senso

(C) Door/Area

(D) Proximity

(E) Pressure

(I) SSR/

(M) Tacho/ Speed/ Pulse meter

(P) Switching mode power supply

motor& Driver&Co

(R) Graphic/ Logic panel

(S) Field network device

Sensing distance by material 20 Sensing distance L(mm) 10 n White Black PCB SUS304 Acrylic (transparent) paper (green) Sensing target(material)

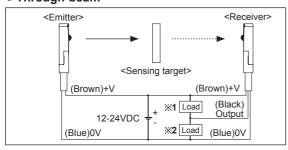
BGS reflective

• BTF15-BDTL / BTF15-BDTL-P

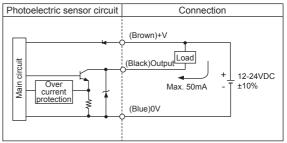
Sensing area characteristic					
Measuring method	Data				
Standard sensing target	18 16 (mu) 12 10 9 9 6 6 4 4 2 2 3 2 1 0 -1 -2 -3 Sensing area (mm)				

Connections

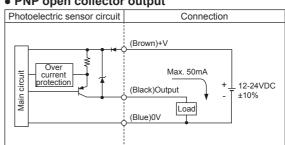
• Through-beam



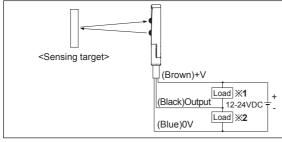
Control output diagram NPN open collector output



• PNP open collector output



• Diffuse reflective/BGS reflective



X1: Load connection for NPN output **%2**: Load connection for PNP output

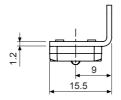
> **Autonics** A-9

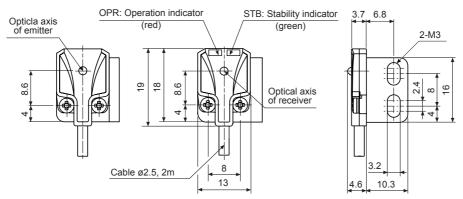
Operation mode

Operation mode	Light ON	Dark ON		
Receiver operation	Received light	Received light		
Receiver operation	Interrupted light	Interrupted light		
Operation indicator	ON	ON		
(red LED)	OFF	OFF		
Transister sutput	ON ON	ON		
Transistor output	OFF	OFF L		

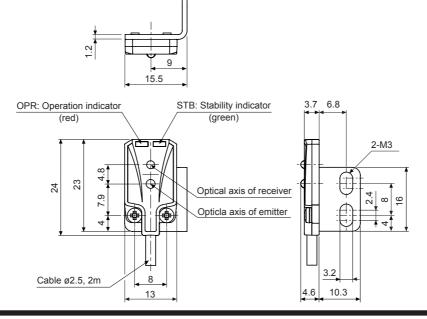
■ Dimensions (unit: mm)

• Through-beam





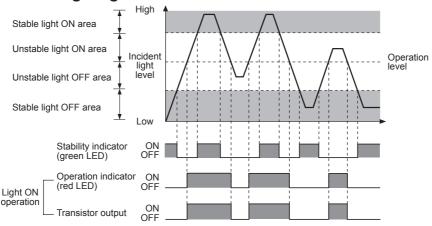
• Diffuse reflective/BGS reflective



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Ultra-Slim and Amplifier Built-in type

Operation timing diagram



XThe waveforms of "Operation indicator" and "Transistor output" are for Light ON operation. They are opposite operation for Dark ON operation.

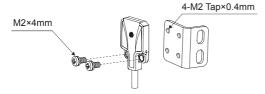
■ Mounting and sensitivity adjustment

For mounting

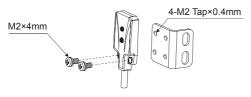
Please use bolts M2 for mounting this sensor and the tightening torque is under 0.3 N·m.

**Do not impact on the unit with hard objects and do not bend the cable part too much. It may cause damage to waterproof function.

• Through-beam



• Diffuse reflective/BGS reflective

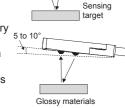


X Notice for BGS reflective type

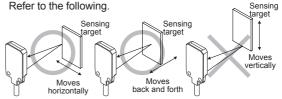
 Make sure that the sensing side of this sensor is parallel with the surface of each sensing object.

 If the sensing object has glossary surface or high reflection, the sensor tilts to 5 to 10° as shown in the figure.

Make sure whether the sensor is influenced by any background objects.



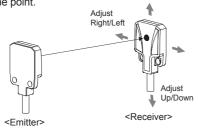
3) Make sure to install the sensor in the proper direction with considering moving direction of sensing objects.



Optical axis adjustment

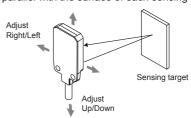
• Through-beam

Set the emitter and the receiver facing each other and adjust these up·down, right·left after to check the point operating the stability indicator. Fix the emitter and the receiver at the center of the point.



• Diffuse reflective/BGS reflective

After place a sensing target, fix it in the middle of position where the stability indicator operates adjusting the sensor to up down, right-left. Make sure that the sensing side of the sensor is parallel with the surface of each sensing target.



(A) Photo electric sensor

(B) Fiber optic

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

> (F) Rotary encoder

(G) Connector/ Socket

(H) Temp.

(I) SSR/ Power controller

(J)

(K)

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching mode power supply

motor& Driver&Controll

(R) Graphic/ Logic panel

(S) Field network device

> T) Software

(U) Other

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